Week 8 Part 3: Euler's Method

Numerical solutions to ODEs are all about approximating a derivative and using that to approximate the solution. We already did that in Week 7, so lets use those approximations.

Consider, $y' = f(t, y)$. Recall

$$
y' = \frac{y(t+h) - y(t)}{h}
$$

Let $t = t_n$ and $t + h = t_{n+1}$. Further, we write $y(t_n) = y_n$ and $y(t_{n+1}) = y_{n+1}$. Then

$$
\frac{y_{n+1}-y_n}{h} \approx f(t_n, y_n),
$$

and therefore

$$
y_{n+1} = y_n + h f(t_n, y_n); \qquad y_0 = y(t_0)
$$
\n⁽¹⁾

This is called the Forward Euler method because we use the forward difference.

We can also do a backward approximation.

$$
y' = \frac{y(t) - y(t - h)}{h}
$$

Let $t = t_{n+1}$ and $t + h = t_n$. Further, we write $y(t_n) = y_n$ and $y(t_{n+1}) = y_{n+1}$. Then

$$
\frac{y_{n+1}-y_n}{h} \approx f(t_{n+1}, y_{n+1}),
$$

and therefore

$$
y_{n+1} = y_n + h f(t_{n+1}, y_{n+1}); \qquad y_0 = y(t_0)
$$
\n⁽²⁾

This is called the Backward Euler method because we use the forward difference. Notice here we have to solve for y_{n+1} since it is implicitly in $f()$.

If you didn't get a chance to take a look a the Week 7 lectures, here is an alternate, but equivalent derivation of the Forward Euler's method:

$$
y'(t) = f(t, y) \Rightarrow f(t, y) \approx \frac{\Delta y}{\Delta t} = \frac{y - y_0}{t - t_0}.
$$

Now lets evaluate f at t_1, y_1 , then we get,

$$
f(t_1, y_1) \approx \frac{y_1 - y_0}{t_1 - t_0} \Rightarrow y_1 - y_0 \approx (t_1 - t_0) f(t_0, y_0) \Rightarrow y_1 \approx y_0 + (t_1 - t_0) f(t_0, y_0).
$$

Look at that! We just developed a formula to approximate y at t_1 by using the information we had for the system at t_0 . If we can approximate the data at t_1 by using the previous time (i.e. t_0), why can't we do this for any time? That is we can approximate y at t_{n+1} via the formula, $y_{n+1} \approx y_n + \Delta t f(t_n, y_n)$. The standard way to write this however is with, $h = \Delta t$, basically a renaming and we usually use $y_0 = y(t_0)$, i.e. the initial condition, and we also drop the \approx and us =. So our general formula is,

$$
y_{n+1} = y_n + h f(t_n, y_n); \ y_0 = y(t_0). \tag{3}
$$

When debugging your codes use the following example, and make sure your values are close to mine. Your values might be ever so slightly off, but not more than say 1e-8.

- (1) $f(t, y) = 3 + t y$, which gives us the equation $y_{n+1} = y_n + h \cdot (3 + t_n y_n)$ where $y_0 = 1$.
	- (a) Here we have $h = 0.1$, so we have the following t's. We get them just by starting at t_0 and incrementing. $t_0 = 0$, $t_1 = 0.1, t_2 = 0.2, t_3 = 0.3, t_4 = 0.4.$ Then we have, $y_1 = y_0 + h \cdot (3 + t_0 - y_0) = 1 + (0.1)(3 + 0 - 1) = 1.2,$ $y_2 = y_1 + h \cdot (3 + t_1 - y_1) = 1.39, y_3 = y_2 + h \cdot (3 + t_2 - y_2) = 1.571, \text{ and } y_4 = y_3 + h \cdot (3 + t_3 - y_3) = 1.7439.$ Lets put this in a table to make it look pretty,
		- $n \parallel 0 \parallel 1 \parallel 2 \parallel 3 \parallel 4$
		- t_n 0 0.1 0.2 0.3 0.4
		- y_n | 1 | 1.2 | 1.39 | 1.571 | 1.7439
	- (b) Hopefully part a gave you a good idea of how we do these problems, so I'll just give the table of values I received when running my code on matlab (remember $h = 0.05$):

(c) Here $h = 0.025$,

(d) Next we solve the equation via integrating factors to get $y = 2 + t - e^{-t}$, and calculating the points gives us the following comparison,

