Last time we asked if matrices of the same size can commute. Lets look at a simple example.

Ex: Consider

Notice

$$
AB = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \neq BA = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}
$$

 $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ ,  $\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$ 

## 2.2 Properties of Matrix Operations

Matrix addition works just like scalar addition.

Matrix multiplication:  $(AB)C = A(BC)$ ,  $A(B+C) = AB + AC$ ,  $AB \neq BA$ . So, in general matrices do not commute. Is there a matrix that commutes with everything?

Consider the  $2 \times 2$  matrix

$$
I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \tag{1}
$$

and a generic  $2 \times 2$  matrix

$$
A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix},
$$

then  $AI = A = IA$ . This is multiplicative identity of matrices, and is called the identity matrix. For a general  $n \times n$  matrix it takes the form,

$$
I_n = \begin{bmatrix} 1 & & & & & \\ & 1 & & 0 & & \\ & & \ddots & & & \\ & & & & \ddots & \\ & & & & & & 1 \end{bmatrix}
$$
 (2)

that is, ones down the diagonal and zeros everywhere else, so for a  $3 \times 3$  matrix it would be

$$
I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
$$

Now lets look at properties of the transpose:  $(A^T)^T = A$ ,  $(A + B)^T = A^T + B^T$ ,  $(cA)^T = c(A^T)$ ,  $(AB)^T = B^T A^T$ . Notice that a dot product of two vectors can also be written as  $v\dot{w} = v^T w$ .

## 1.2 Gaussian Elimination

Now lets go back and do a bunch of Gaussian Elimination problems. Again consider our equation from last time

$$
2u + v + w = 5
$$
  
\n
$$
4u - 6v = -2
$$
  
\n
$$
-2u + 7v + 2w = 9
$$
\n(3)

we will write this as an augmented matrix by appending the right hand side (RHS) to the coefficient matrix,

$$
2\begin{bmatrix} 2 & 1 & 1 & | & 5 \\ 4 & -6 & 0 & | & -2 \\ -2 & 7 & 2 & | & 9 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 1 & | & 5 \\ 0 & -8 & -2 & | & -12 \\ -2 & 7 & 2 & | & 9 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 1 & | & 5 \\ 0 & -8 & -2 & | & -12 \\ 0 & 8 & 3 & | & 14 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 1 & | & 5 \\ 0 & -8 & -2 & | & -12 \\ 0 & 0 & 1 & | & 2 \end{bmatrix}
$$

This means  $\boxed{w = 2}$ , then we plug into the second equation to get  $\boxed{v = 1}$ , and finally the first to get  $\boxed{u = 1}$ .

The elements down the diagonal are called pivots. The augmented matrix is said to be in row-echelon form. Th original matrix,

$$
\begin{bmatrix} 2 & 1 & 1 \ 0 & -8 & -2 \ 0 & 0 & 1 \end{bmatrix}
$$

is said to be in upper triangular form.

Here are some problems we did from the book pp 22 - 23. 25)

$$
3\begin{bmatrix} 1 & 3 & | & 11 \\ 3 & 1 & | & 9 \end{bmatrix} = \begin{bmatrix} 1 & 3 & | & 11 \\ 0 & -8 & | & -12 \end{bmatrix} \Rightarrow \boxed{y = 3} \Rightarrow \boxed{x = 2};
$$
  
27)  

$$
-2\begin{bmatrix} -1 & 2 & | & 3/2 \\ 2 & -4 & | & 3 \end{bmatrix} = \begin{bmatrix} -1 & 2 & | & 3/2 \\ 0 & 0 & | & -6 \end{bmatrix}
$$
  
Clearly this matrix is singular, and since the RHS is nontrivial it will have no solutions.

31) 3 2  $\lceil$  $\overline{1}$  $1 \t 0 \t -3 \t -2$ 3 1 −2 | 5 2 2 1 | 4 1  $\Big| =\frac{1}{2}$  $\lceil$  $\overline{\phantom{a}}$  $1 \t0 \t-3 \t-2$ 0 1 7 | 11 0 2 7 | 8 1  $\vert$  =  $\lceil$  $\overline{\phantom{a}}$  $1 \t 0 \t -3 \t -2$ 0 1 7 | 11  $0 \t 0 \t -7 \t -14$ 1  $\overline{1}$ then  $x_3 = 2, x_2 = -3, x_1 = 4.$ 33) 2 4  $\lceil$  $\overline{1}$ 2 0 3 | 3 4 −3 7 | 5 8 −9 15 | 10 1  $\Big| = \Big|_3$  $\lceil$  $\overline{1}$ 2 0 3 | 3 0 −3 1 | −1 0 −9 3 | −2 1  $\vert$  =  $\lceil$  $\overline{1}$ 2 0 3 | 3 0 −3 1 | −1  $0 \quad 0 \quad 0 \quad | \quad 1$ 1  $\overline{1}$ 

Clearly this matrix is singular, and since the RHS is nontrivial it will have  $\sqrt{\frac{1}{100}}$  solutions