Last time we asked if matrices of the same size can commute. Lets look at a simple example.

Ex: Consider

Notice

$$AB = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \neq BA = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

 $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$ 

## 2.2 Properties of Matrix Operations

Matrix addition works just like scalar addition.

Matrix multiplication: (AB)C = A(BC), A(B + C) = AB + AC,  $AB \neq BA$ . So, in general matrices do not commute. Is there a matrix that commutes with everything?

Consider the  $2 \times 2$  matrix

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \tag{1}$$

and a generic  $2 \times 2$  matrix

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix},$$

then AI = A = IA. This is multiplicative identity of matrices, and is called the <u>identity matrix</u>. For a general  $n \times n$  matrix it takes the form,

$$I_{n} = \begin{bmatrix} 1 & & & \\ & 1 & & 0 \\ & & \ddots & \\ & 0 & & \ddots \\ & & & & 1 \end{bmatrix}$$
(2)

that is, ones down the diagonal and zeros everywhere else, so for a  $3 \times 3$  matrix it would be

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Now lets look at properties of the transpose:  $(A^T)^T = A$ ,  $(A + B)^T = A^T + B^T$ ,  $(cA)^T = c(A^T)$ ,  $(AB)^T = B^T A^T$ . Notice that a dot product of two vectors can also be written as  $v\dot{w} = v^T w$ .

## 1.2 Gaussian Elimination

Now lets go back and do a bunch of Gaussian Elimination problems. Again consider our equation from last time

$$2u + v + w = 54u - 6v = -2-2u + 7v + 2w = 9$$
(3)

we will write this as an augmented matrix by appending the right hand side (RHS) to the coefficient matrix,

$$2\begin{bmatrix}2&1&1&|&5\\4&-6&0&|&-2\\-2&7&2&|&9\end{bmatrix} = \begin{bmatrix}2&1&1&|&5\\0&-8&-2&|&-12\\-2&7&2&|&9\end{bmatrix} = \begin{bmatrix}2&1&1&|&5\\0&-8&-2&|&-12\\0&8&3&|&14\end{bmatrix} = \begin{bmatrix}2&1&1&|&5\\0&-8&-2&|&-12\\0&0&1&|&2\end{bmatrix}$$

This means w = 2, then we plug into the second equation to get v = 1, and finally the first to get u = 1.

The elements down the diagonal are called <u>pivots</u>. The augmented matrix is said to be in <u>row-echelon</u> form. Th original matrix,

$$\begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

is said to be in upper triangular form.

Here are some problems we did from the book pp 22 - 23. 25)

$$3 \begin{bmatrix} 1 & 3 & | & 11 \\ 3 & 1 & | & 9 \end{bmatrix} = \begin{bmatrix} 1 & 3 & | & 11 \\ 0 & -8 & | & -12 \end{bmatrix} \Rightarrow \boxed{y=3} \Rightarrow \boxed{x=2};$$
27)
$$-2 \begin{bmatrix} -1 & 2 & | & 3/2 \\ 2 & -4 & | & 3 \end{bmatrix} = \begin{bmatrix} -1 & 2 & | & 3/2 \\ 0 & 0 & | & -6 \end{bmatrix}$$
Clearly this matrix is singular, and since the RHS is nontrivial it will have no solutions.

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 $3\begin{bmatrix}1 & 0 & -3 & | & -2\\3 & 1 & -2 & | & 5\\2 & 2 & 1 & | & 4\end{bmatrix} = 2\begin{bmatrix}1 & 0 & -3 & | & -2\\0 & 1 & 7 & | & 11\\0 & 2 & 7 & | & 8\end{bmatrix} = \begin{bmatrix}1 & 0 & -3 & | & -2\\0 & 1 & 7 & | & 11\\0 & 0 & -7 & | & -14\end{bmatrix}$ then  $x_3 = 2, x_2 = -3, x_1 = 4.$ 31)33)

Clearly this matrix is singular, and since the RHS is nontrivial it will have no solutions