

(1) (a) We take the Wronskian,

$$W(f, g) = \begin{vmatrix} e^{2t} & g \\ 2e^{2t} & g' \end{vmatrix} = e^{2t}g' - 2e^{2t}g = 3e^{4t}.$$

Then we solve the ODE,

$$g' - 2g = 3e^{2t} \Rightarrow \mu = \exp\left(-\int^t 2d\tau\right) = e^{-2t} \Rightarrow e^{-2t}g = \int^t 3d\tau = 3t \Rightarrow g = 3te^{2t}.$$

(b) (i) From the Wronskian we get that they are L.I.,

$$W(y_1, y_2) = \begin{vmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{vmatrix} = 1 \neq 0.$$

(ii) From the Wronskian we get that they are L.I.,

$$W(y_1, y_2) = \begin{vmatrix} x & xe^x \\ 1 & e^x + xe^x \end{vmatrix} = x^2e^x \neq 0.$$

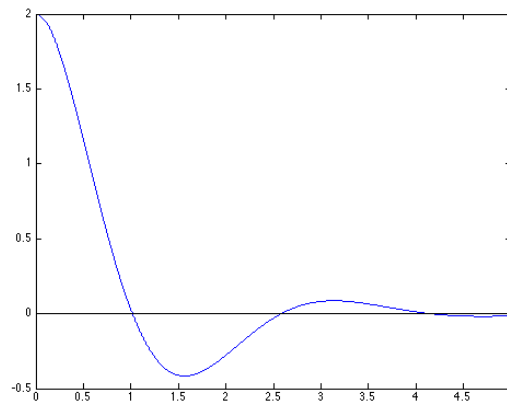
(2) The characteristic polynomial gives,  $r^2 + 2r + 5 = 0 \Rightarrow r = -1 \pm 2i$ , then our general solution is

$$y = e^{-t}(A \cos 2t + B \sin 2t)$$

Our initial conditions give us,  $y(0) = A = 2$  and  $y'(0) = -2 + 2B = 0 \Rightarrow B = 1$ , then our solution is

$$y = e^{-t}(2 \cos 2t + \sin 2t).$$

Your sketch should look like,



(3) Plugging the first solution into the ODE gives  $t^2(2t^{-3}) + 3t(-t^{-2}) + t^{-1} = 0$ . Now, for reduction of order let  $y = v(t)t^{-1}$ , which gives the derivatives,

$$y' = v't^{-1} - t^{-2}v \Rightarrow y'' = v''t^{-1} - 2t^{-2}v' + 2t^{-3}.$$

Plugging in to the ODE gives,

$$v''t - 2v' + 2t^{-1} + 3v' - 3vt^{-1} + vt^{-1} = tv'' + v' = 0.$$

Let  $u = v'$ , then we get,

$$u' = -\frac{1}{t}u \Rightarrow \ln u = \int \frac{dt}{t} = -\ln t + C_0 \Rightarrow u = \frac{k}{t} \Rightarrow v = k \ln t + C_1$$

Then,  $y = k \ln t/t + C_1/t$ , so  $y_2 = \ln t/t$ .

(4) (a) We employ the characteristic polynomial,  $2r^2 + 3r + 1 = 0 \Rightarrow r = -3/4 \pm 1/4 = -1, -1/2$ . Then the characteristic solution is,  $y_c = c_1e^{-t/2} + c_2e^{-t}$ . Then our particular solution is,

$$y_p = A_1t^2 + A_2t + A_3 + B_1 \cos t + B_2 \sin t \Rightarrow y_p' = 2A_1t + A_2 - B_1 \sin t + B_2 \cos t \Rightarrow y_p'' = 2A_1 - B_1 \cos t - B_2 \sin t.$$

Plugging into the ODE gives,

$$4A_1 - 2B_1 \cos t - 2B_2 \sin t + 6A_1t + 3A_2 - 3B_1 \sin t + 3B_2 \cos t + A_1t^2 + A_2t + A_3 + B_1 \cos t + B_2 \sin t = t^2 + 3 \sin t.$$

Grouping terms gives,

$$A_1 t^2 + (A_2 + 6A_1)t + (4A_1 + 3A_2 + A_3) + (3B_2 - B_1) \cos t - (3B_1 + B_2) \sin t = t^2 + 3 \sin t.$$

Then we get  $A_1 = 1$ ,  $A_2 = -6$ ,  $A_3 = 14$ ,  $B_1 = -9/10$ ,  $B_2 = -3/10$ . Then our full general solution is,

$$y = c_1 e^{-t/2} + c_2 e^{-t} + t^2 - 6t + 14 - \frac{9}{10} \cos t - \frac{3}{10} \sin t.$$

(b) We have to solve for the characteristic solution first,  $r^2 + 3r = r(r + 3) = 0$ , then  $y_c = c_1 + c_2 e^{-3t}$ , so our particular solution is,

$$y_p = t(A_4 t^4 + A_3 t^3 + A_2 t^2 + A_1 t + A_0) + t(B_2 t^2 + B_1 t + B_0)e^{-3t} + D_1 \sin 3t + D_2 \cos 3t.$$

(5) Plugging  $y_1 = t$  into the ODE gives,  $-t(t + 2) + t(t + 2) = 0$  and  $y_2 = te^t$  gives,

$$2t^2 e^t + t^3 e^t - t^2 e^t - t^3 e^t - 2te^t - 2t^2 e^t + t^2 e^t + 2te^t = 0.$$

Taking the Wronskian gives,

$$W(y_1, y_2) = \begin{vmatrix} t & te^t \\ 1 & te^t + e^t \end{vmatrix} = t^2 e^t.$$

We recall our variation of parameters formula,

$$y = -y_1 \int \frac{y_2 f(t)}{W(y_1, y_2)} dt + y_2 \int \frac{y_1 f(t)}{W(y_1, y_2)} dt.$$

We do the integrals individually,

$$\int \frac{y_2 f(t)}{W(y_1, y_2)} dt = \int \frac{(te^t)(2t)}{t^2 e^t} dt = -2t + C_1; \quad \int \frac{y_1 f(t)}{W(y_1, y_2)} dt = \int \frac{t(2t)}{t^2 e^t} dt = 2 \int e^{-t} dt = -2e^{-t} + C_2$$

Plugging these back into our equation gives,

$$y = -2t^2 + C_1 t - 2t + C_2 te^t = -2t^2 + C_3 t + C_2 te^t.$$

Which means,  $y_p = -2t^2$ .

(6) (a) Our IVP is,

$$\frac{1}{2}u'' + 2u' + 64u = 0; \quad u(0) = 0, \quad u'(0) = \frac{1}{4}.$$

(b) Our characteristic polynomial gives,  $r^2/2 + 2r + 64 = 0 \Rightarrow r = -2 \pm i\sqrt{124}$ . Then our general solution is,

$$u = e^{-2t}(A \cos \sqrt{124}t + B \sin \sqrt{124}t).$$

Then from the initial conditions we get,  $u(0) = A = 0$  and  $u'(0) = B\sqrt{124} = 1/4$ , so  $B = 1/4\sqrt{124}$ . Then our solution is,

$$u = \frac{1}{4\sqrt{124}} e^{-2t} \sin \sqrt{124}t$$

(c) Your plot should look as follows,

